

# **SurfRef Project**

**TWCWG3**

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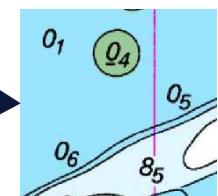
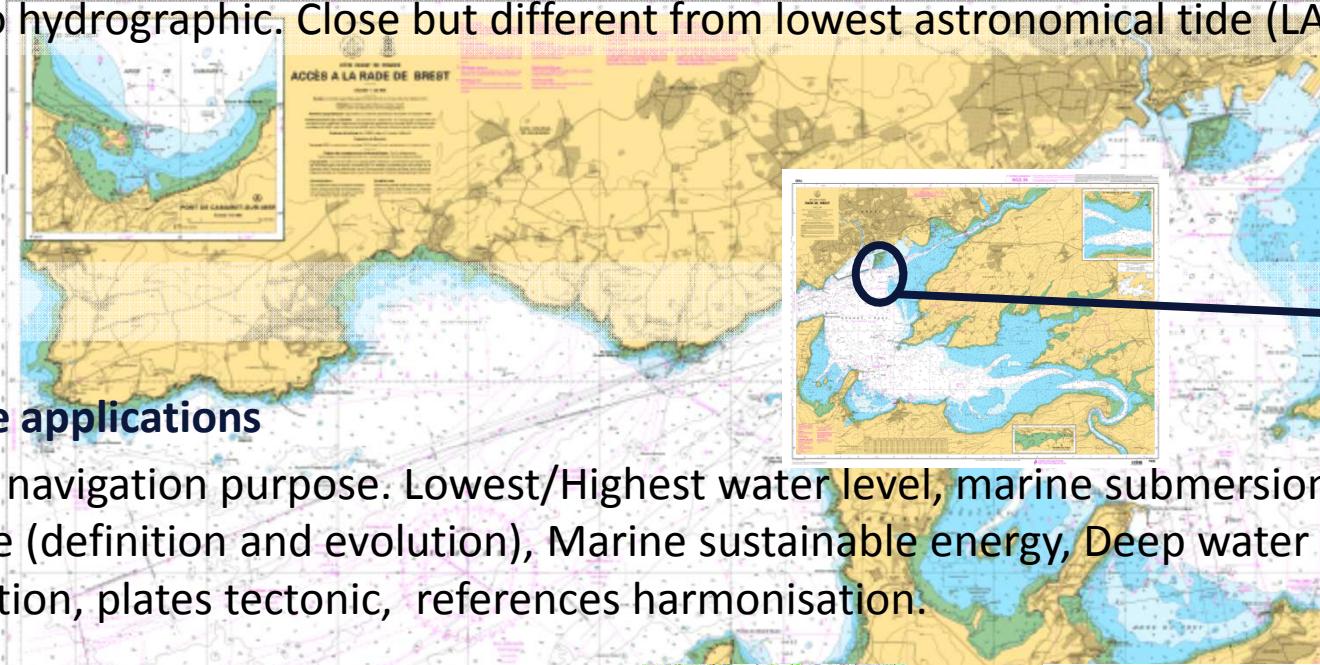
**2018-04-18**



# Marine reference surfaces: For who, for what?

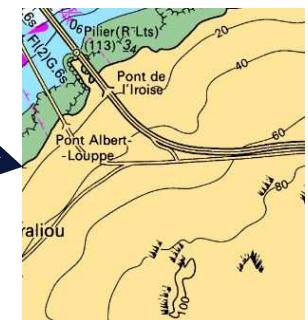
## 2 needs

- \* Ensure a stable water level reference (this need is guided by scientific improvement and applications closely tied to IHO recommendations)
- Ensure a minimum water level better than 0.15 m : Chart datum. For the project ⇔ Zero hydrographic. Close but different from lowest astronomical tide (LAT).



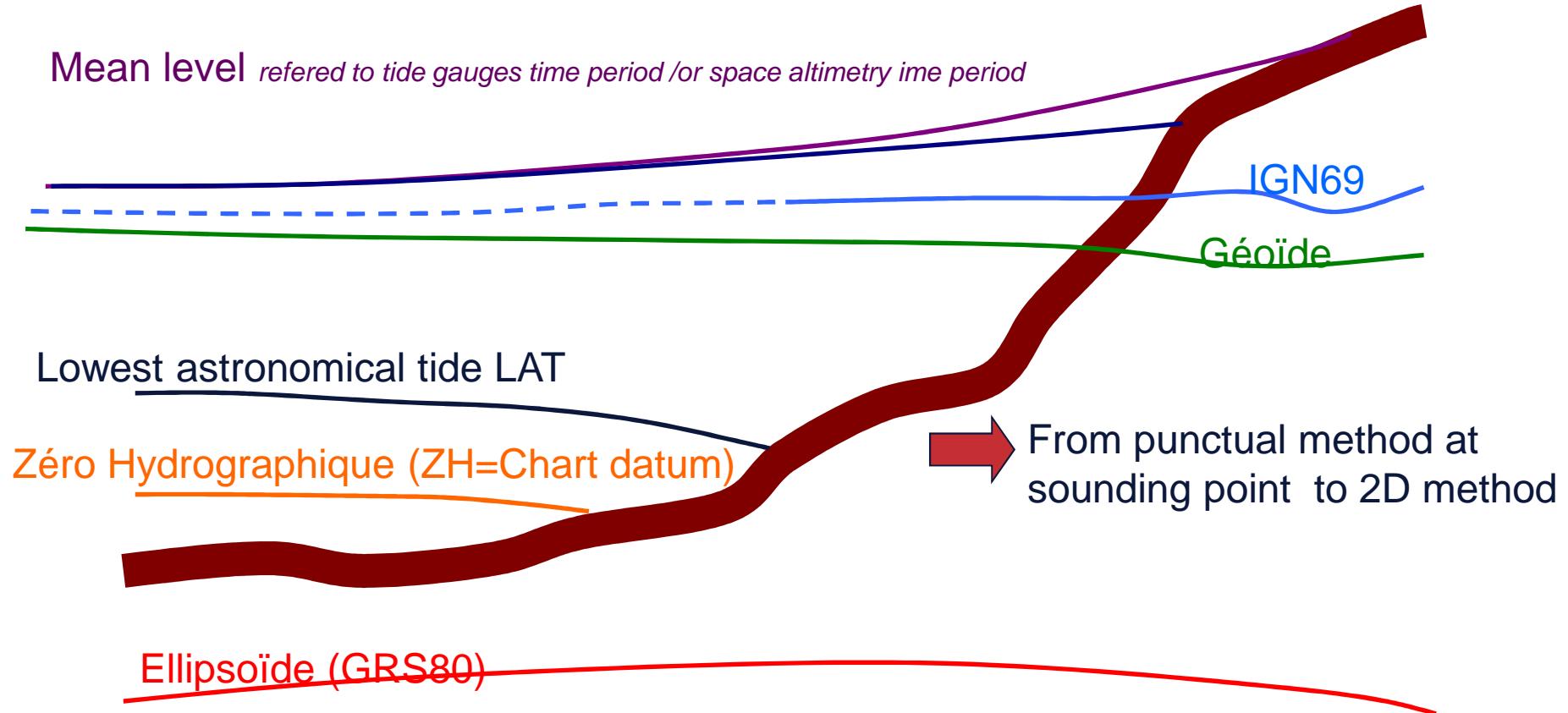
## Multiple applications

- \* Safety navigation purpose. Lowest/Highest water level, marine submersion, coastline (definition and evolution), Marine sustainable energy, Deep water exploitation, plates tectonic, references harmonisation.



Source: M-F Lequentrec-Lalancette, journée ITRS, St-Mandé juin 2015

# Starting point



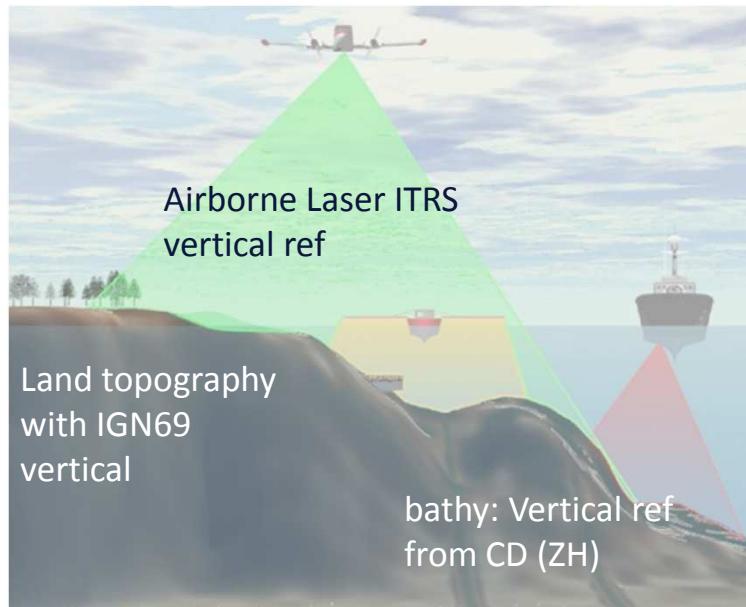
Basics from BATHYELLI = BATHYmétrie on ELLIpsoïde (2006, L. Pineau et al., G. Jan et al (2009), Y-M Tanguy et al. 2014)

# *Marine surfaces of reference*

Need to use a common vertical reference frame (ellipsoid) => GRS80, legal reference system, WGS84. (cf; IHO recommendations and the uses)

From [NSHC32](#) : “TWG members agreed that in future for exchange of data, the GRS80 ellipsoid should be used as common reference frame.”

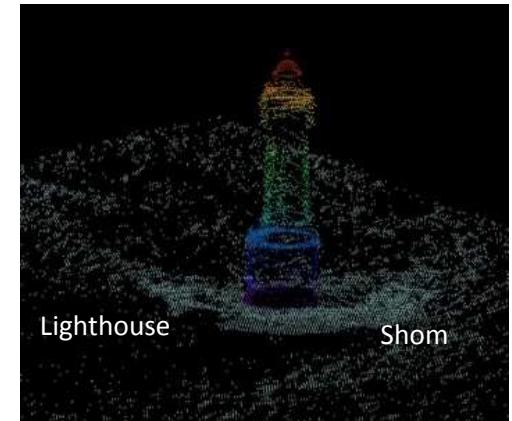
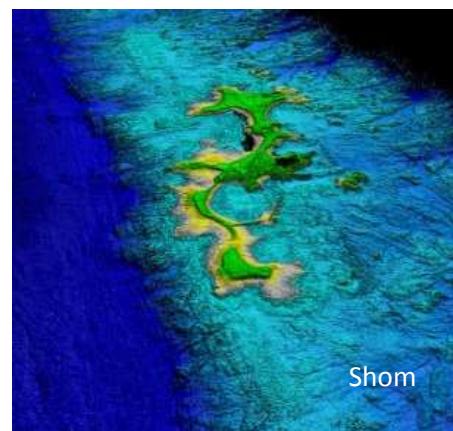
([https://www.ihodata.int/mtg\\_docs/com\\_wg/IHOTC/IHOTC8/IHOTC8-3-6-1.pdf](https://www.ihodata.int/mtg_docs/com_wg/IHOTC/IHOTC8/IHOTC8-3-6-1.pdf), p 5)



Source image : M-F Lequentrec-Lalancette, journée ITRS, St-Mandé 2015

Expected improvement : Litto3D (Shom, IGN)

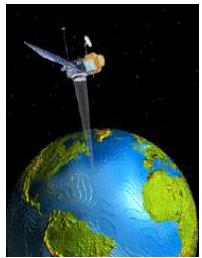
The Litto3D program aims to produce a continuous land-sea altimetric digital model of the coastal fringe.



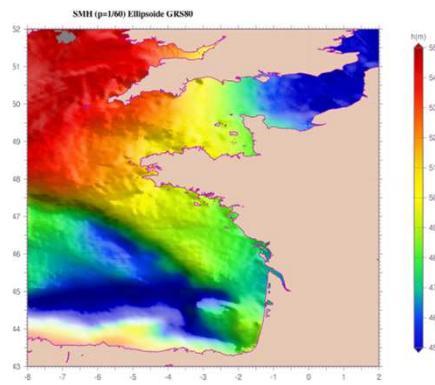
<https://www.geoportail.gouv.fr/donnees/litto3d>

<http://www.shom.fr/les-activites/projets/modele-numerique-terre-mer/>

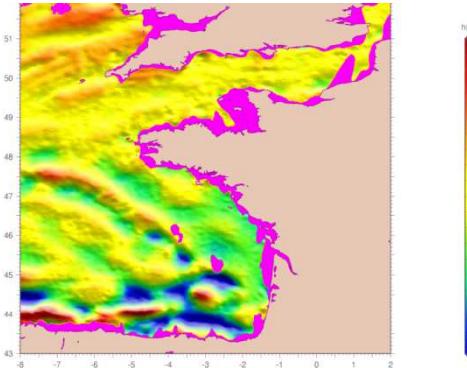
<http://diffusion.shom.fr/produits/altimetrie-littorale>



FR method → 3 technics



Mean sea surface derived for space altimetry



Error on Smh/ GRS80 (Source CLS)



Tide gauges

Improvement : Increasing density of the GNSS pushes forward hydrography and gives

relief to the reference heights.



GPS : Land station



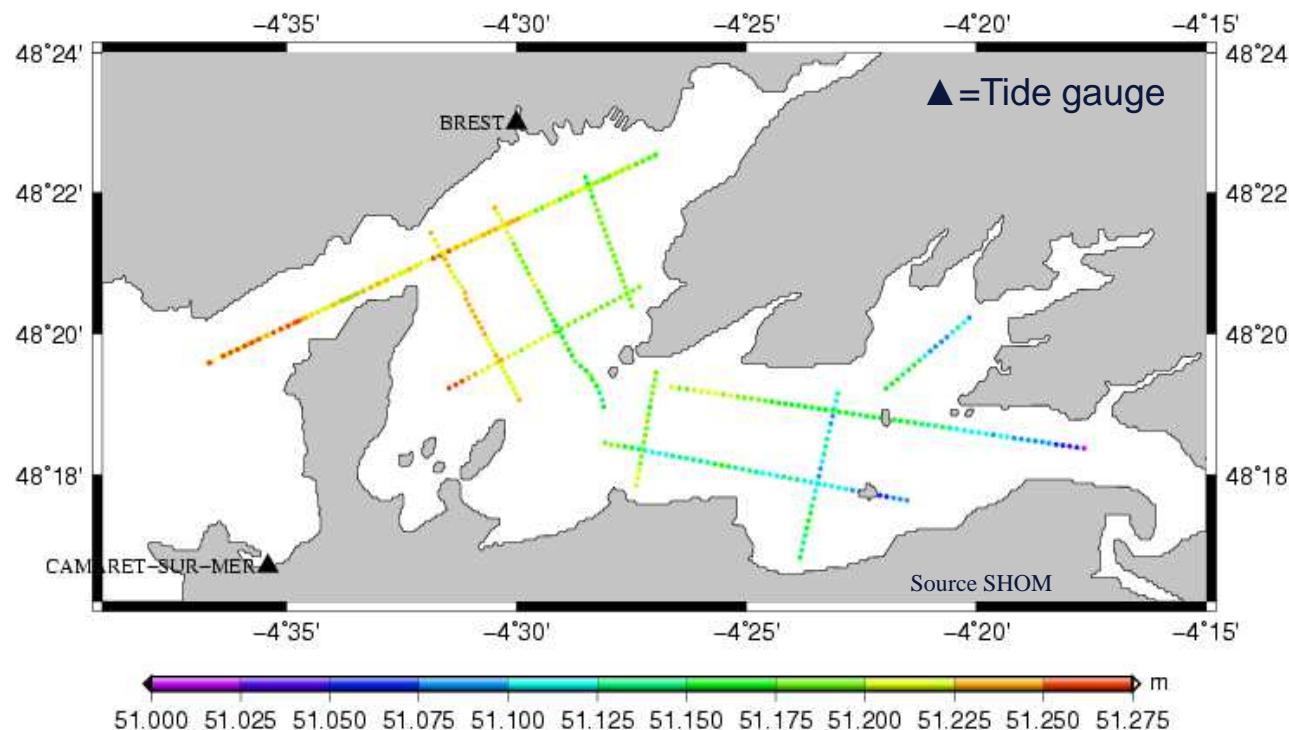
Ocean GPS : Kinetic mode



GPS buoy

# GPS Measurement

## From profils towards a GPS MSS

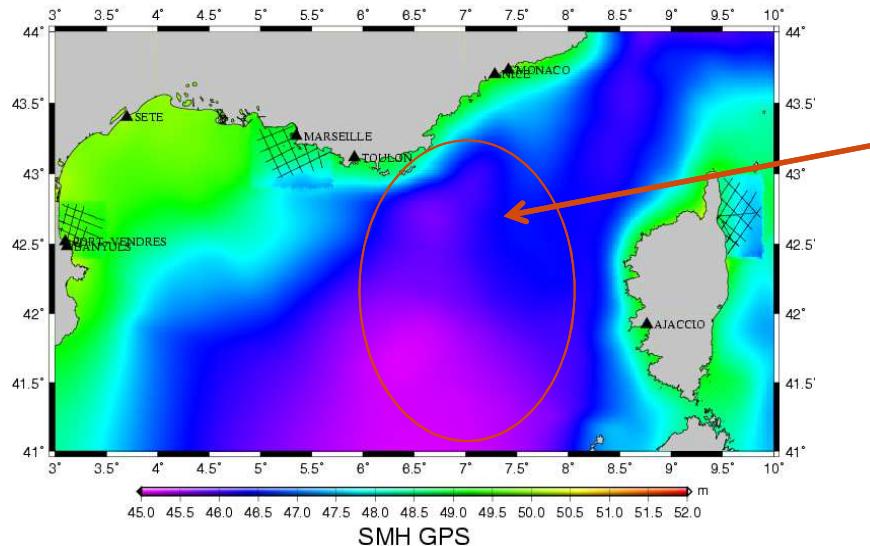
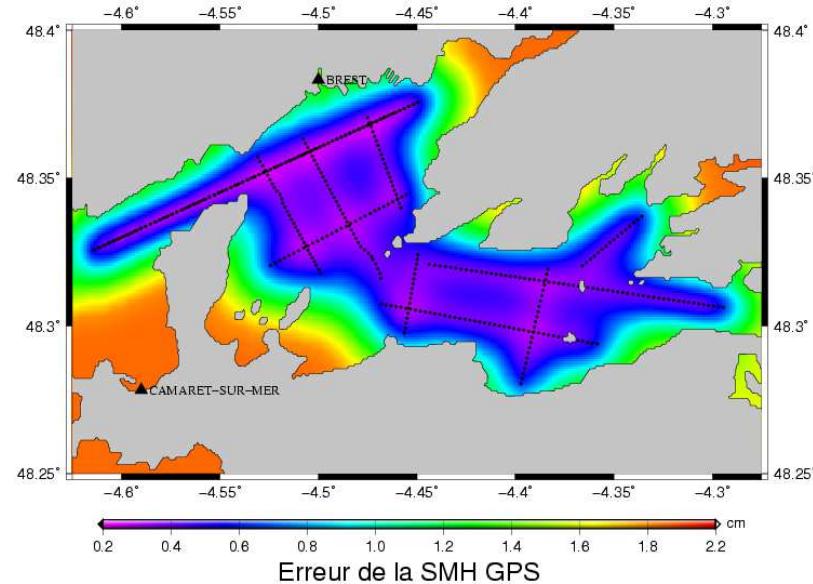
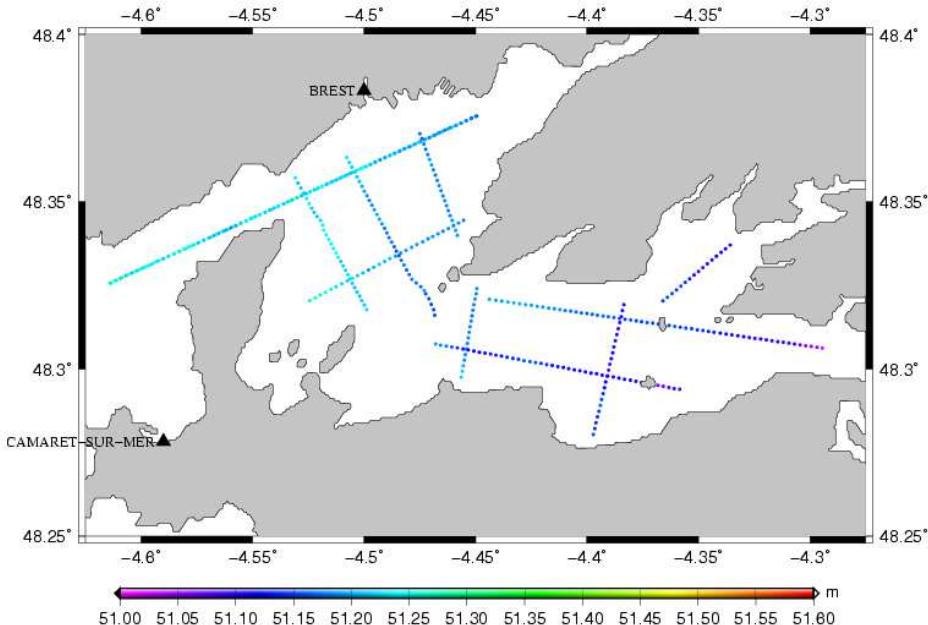


- Height minimisation at crossover point.
- Optimisation to built matrix more easy to inverse during the GPS MSS process.

Nb de pts	Min [m]	Max [m]	Mean [m]	STD [m]	Distance between 2 points [m]
421	51.0080	51.2810	51.1826	0.0488	187

# Interpolation

Covariances estimation using analytical models



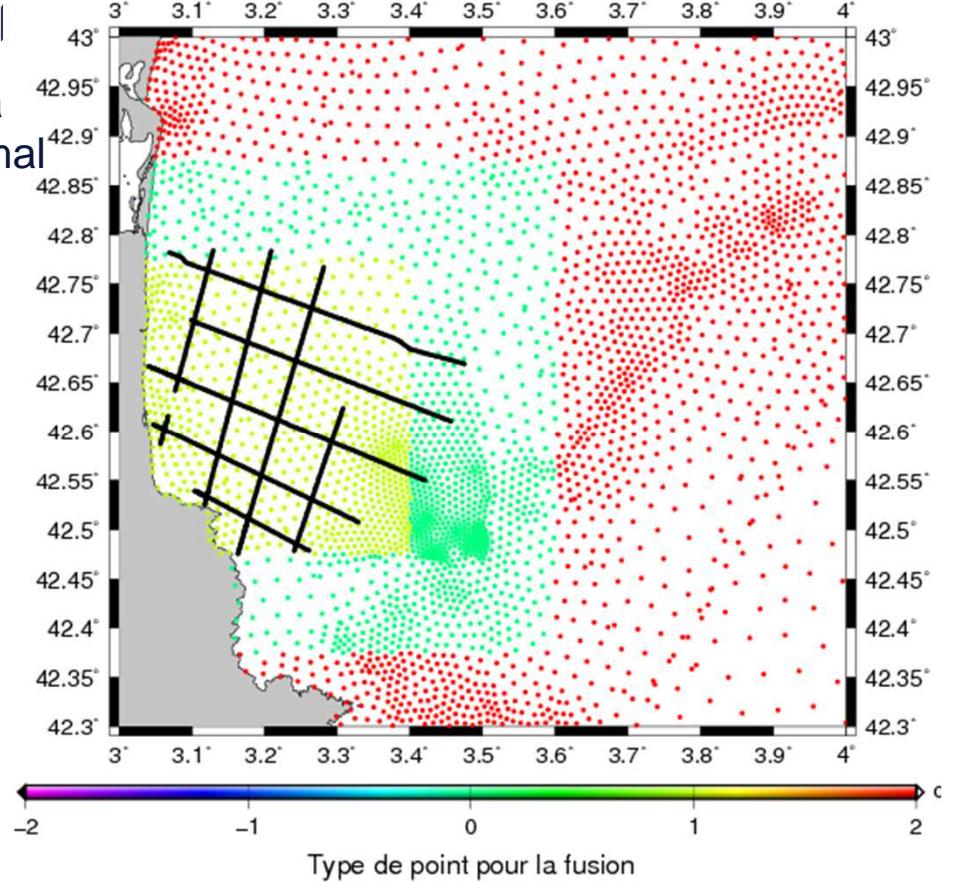
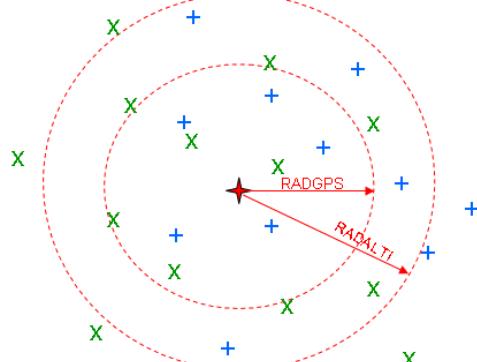
For area where there is no GPS, no tide gauge measurements, geoid height is used (here, EGG97, computation done in 2009)

# Optimal interpolation between GPS, ALTIMETRY, DATA SMH

## ➤ Data selection (MSS GPS and MSS ALT)

➤ At each grid point of the threshold area, data fusion is done : SMH GPS and ALTI in the optimal interpolation radius.

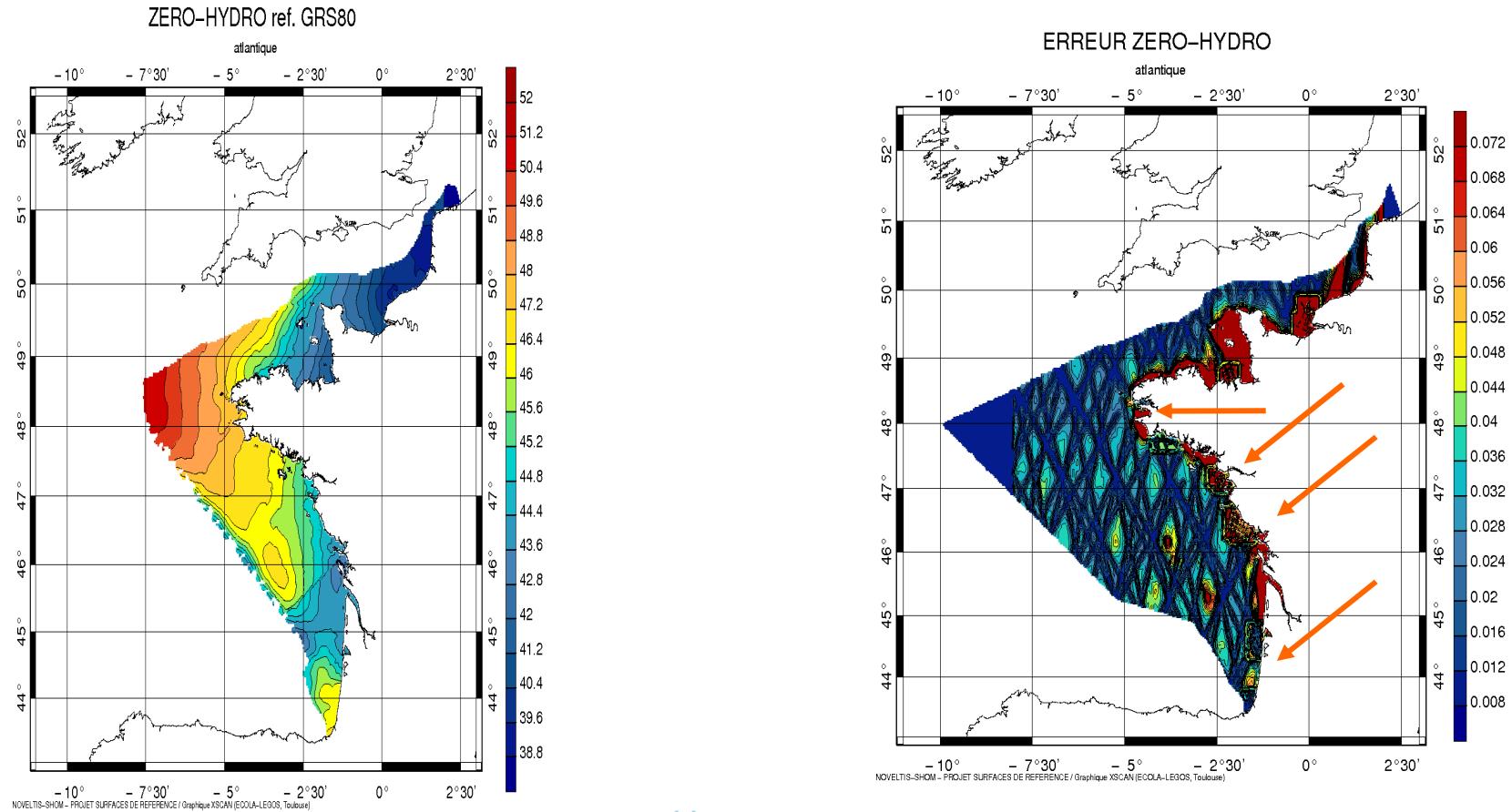
➤ optimal radius are RADGPS et RADALTI,



Type de point pour la fusion

- threshold area (0)
- Valide GPS area (1)
- Valide alti area (2)

# Merged reference surfaces result (Bathyelli)



<http://data.shom.fr>

Access to :

ZH (Fr chart datum)

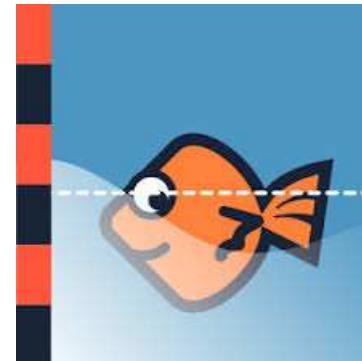
Lowest astronomical tide (used for NSHC LAT comparison)

Mean water level (niveau moyen), GRS80 ITRS ellipsoid, IGN69.

# SurfRef study : Surfaces of reference



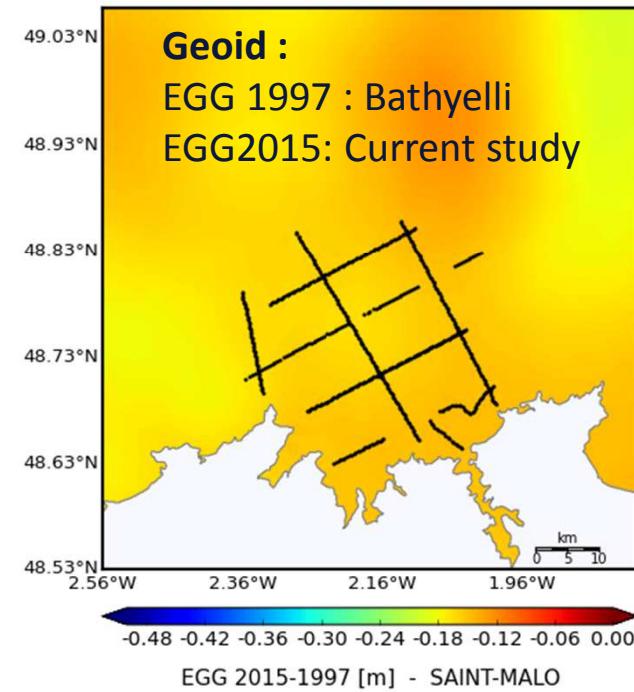
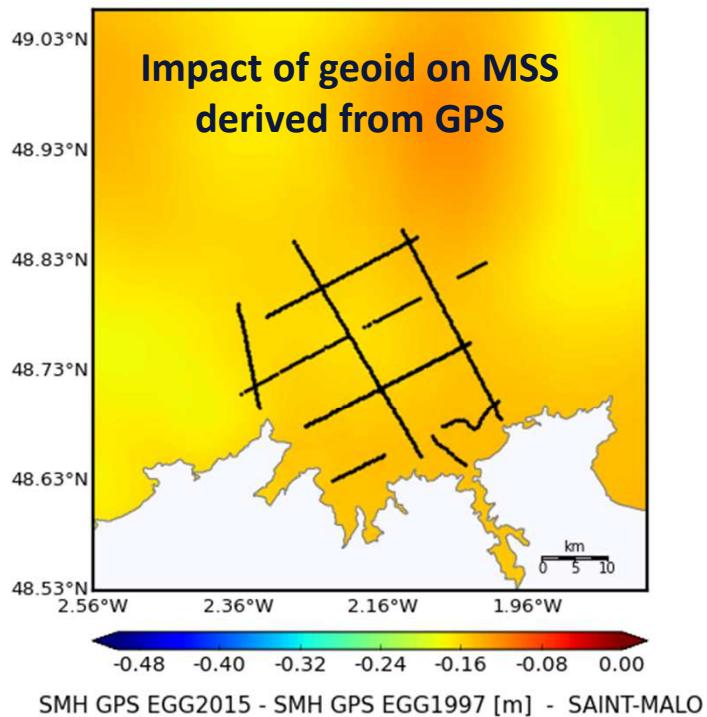
- Importance of a global reference system as precise as possible
- Marine improvement → Importance of the IHO framework and projects.
- Method and technology improvement suggested for this study : Geoid impact, Coupling marine vertical reference and Litto3d Shom/IGN land-sea mapping, GNSS precise positioning.



Src image: [Android-logiciels.fr](http://Android-logiciels.fr)

## Test : Impact of the geoid on the SMH derived from altimetry and GPS

- EGG2015 vs. EGG97

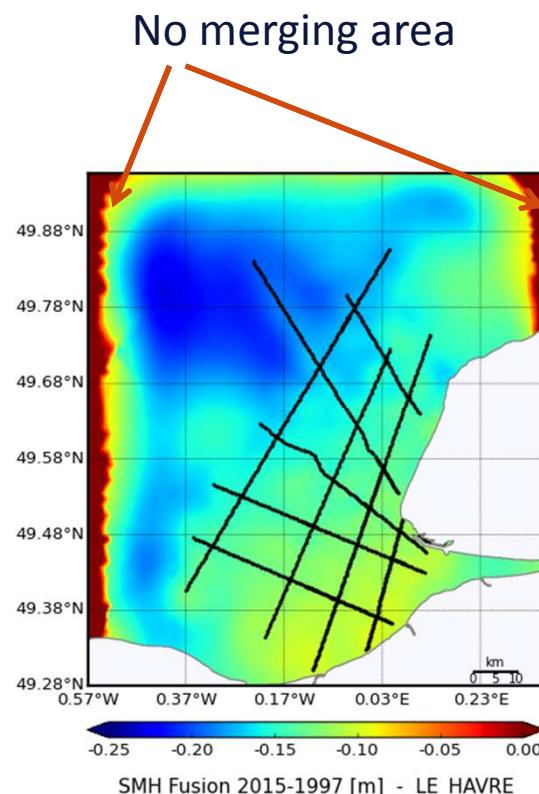
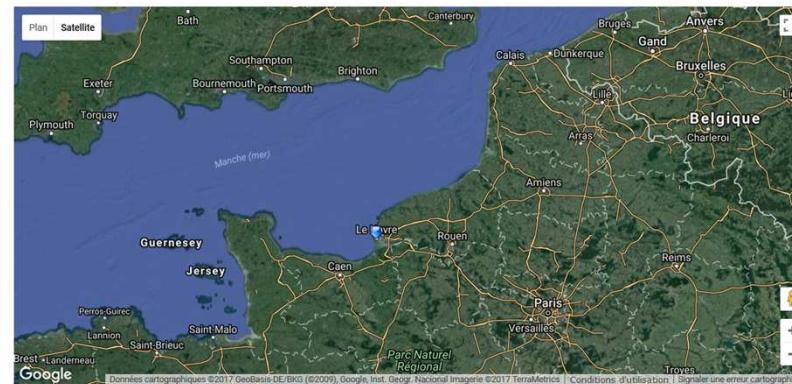


## Preliminary results : test

Source : SurfRef project E. Renault (Shom)

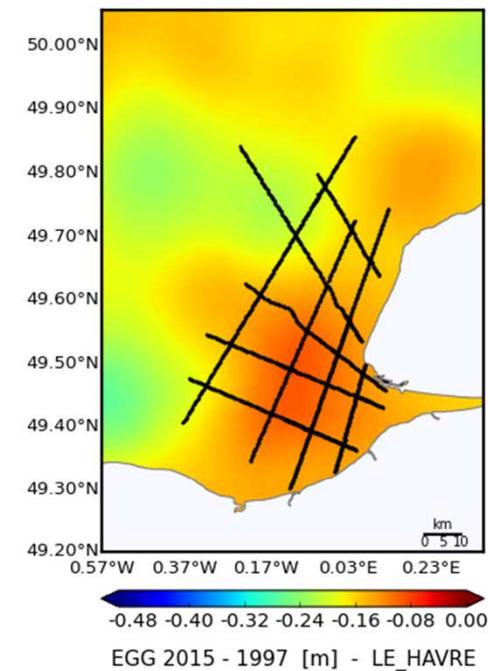
# Test : Impact of the geoid on the SMH derived form altimetry and GPS Le Havre

Latitude : 49.4938 °N  
Longitude : 0.1077 °E



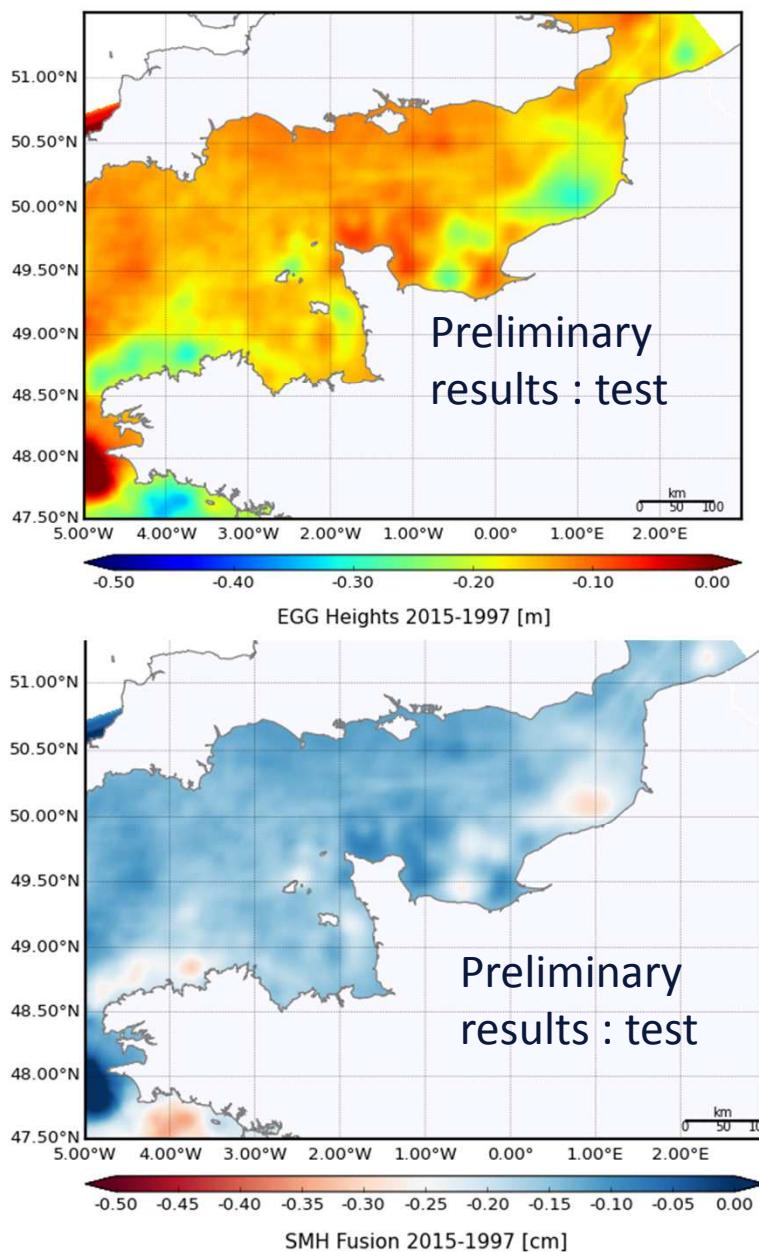
Preliminary  
results : test

Need to be improved at  
Le Havre (GPS survey?  
Adding data?) and at the  
North border France.



Source : SurfRef project  
E. Renault (Shom)

# Test : Impact of the geoid on the SMH derived form altimetry and GPS



Source : SurfRef project  
E. Renault (Shom)

# Impact du géoïde

## European Gravimetric Geoid EGG2015

- Constant improvement of EGG97: releases 1997, 2008, 2015.
  - Since the major re-computation of 2008:
    - Higher number of gravity field data sets
    - 5 releases of GOCE Global Model
    - Improvement of the modelling method
- EGG2015 Release

EGG1997	EGG2008	EGG2015
2,684,133 (744 sources)	Project gravity data base 5,355,206 (718 sources)	6,100,190 (766 sources)
335,124 (KMS1996)	Other gravity data sources 195,840 (ArcGP) 13,222,260 (1' x 1' alt.) 120,747 (EGM2008 fillins)	389,196 (ArcGP) 13,222,260 (1' x 1' alt.) 120,807 (EGM2008 fillins)
- <b>3,019,257 (Total)</b>	<b>18,894,053 (Total)</b>	<b>19,832,453 (Total)</b>
7.5" ... 5' resol. 700 million elev. 15' x 20' RTM	Terrain data base 1" ... 30" resol. 8.3 billion elev. 15' x 20' RTM	1" ... 30" resol. 8.3 billion elev. 15' x 20' RTM
EGM1996 ( $l_{\max}=360$ )	Global geopotential model EGM2008 ( $l_{\max}=360/2190$ )	GOC005S ( $l_{\max}=280$ )
Computation procedure	Remove-restore technique, spectral combination (1DFFT) GRS80, zero-tide system, EVRS	
Computation grid	$25^{\circ} - 77^{\circ}\text{N}, 35^{\circ}\text{W} - 67.4^{\circ}\text{E}$ 1.0' x 1.5' $3,120 \times 4,096$ pts.	
	$25^{\circ} - 85^{\circ}\text{N}, 50^{\circ}\text{W} - 70^{\circ}\text{E}$ 1.0' x 1.0' $3,600 \times 7,200$ pts.	$25^{\circ} - 85^{\circ}\text{N}, 50^{\circ}\text{W} - 70^{\circ}\text{E}$ 1.0' x 1.0' $3,600 \times 7,200$ pts.

Table 1: Characteristics of EGG from 1997 to 2015. (Denker, 2015)

Source: Denker, « A new European Gravimetric (Quasi)Geoid EGG2015 », 26th IUGG General Assembly (Session 3), Prague, June 22 – July 2, 2015

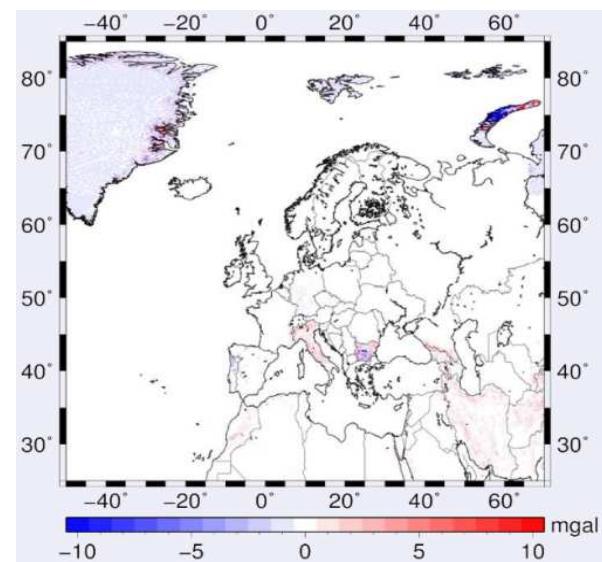
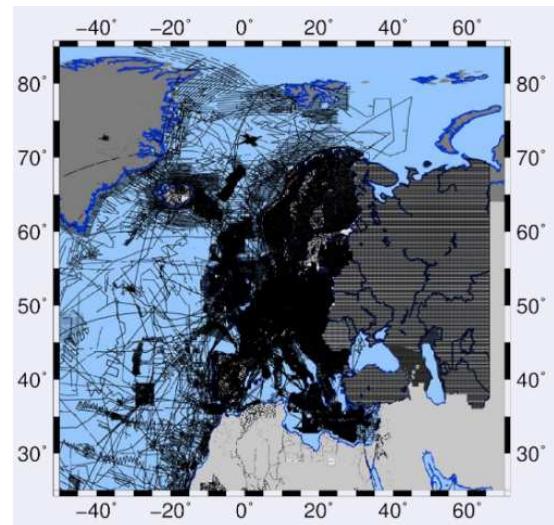
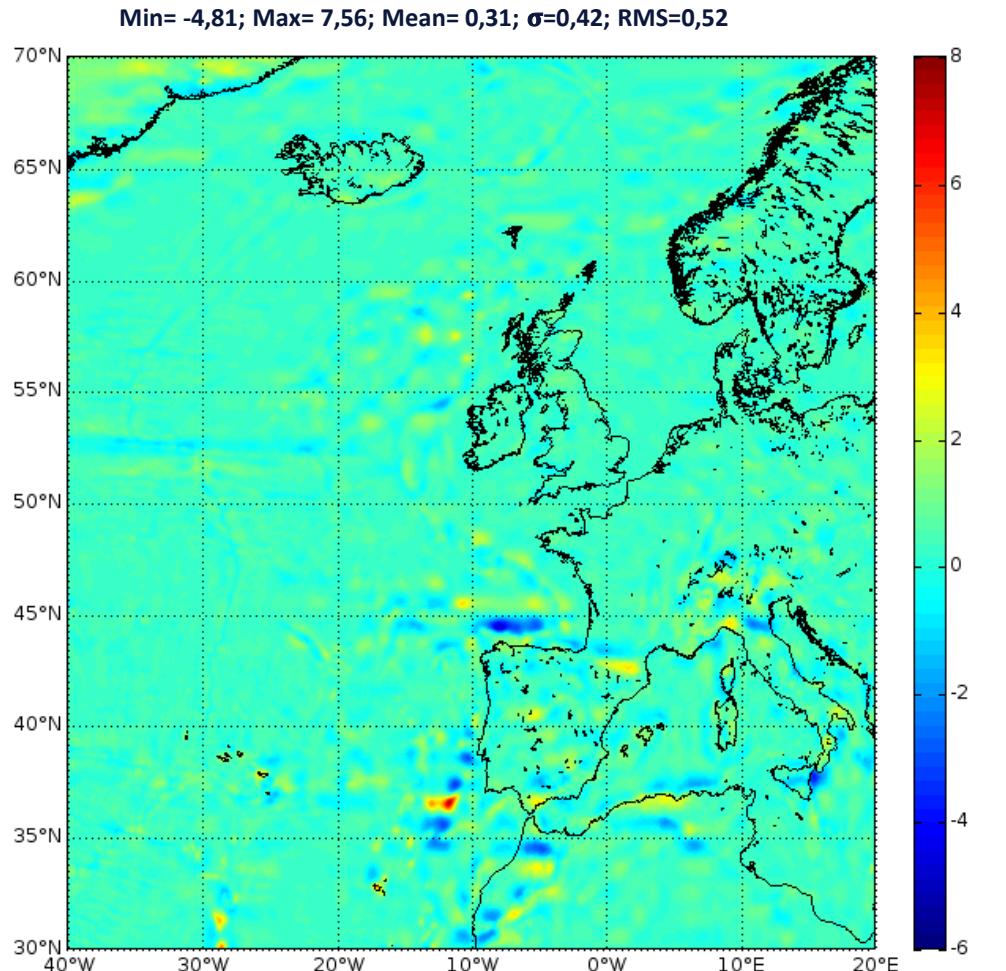


Figure 1 : Gravity dataset for EGG2015 (up) and differences between EGG2015 and the precedent version EGG2008 (down). (Denker, 2015)

## Differences between EGG2015 and EGM08: possible improvement for SurfRef



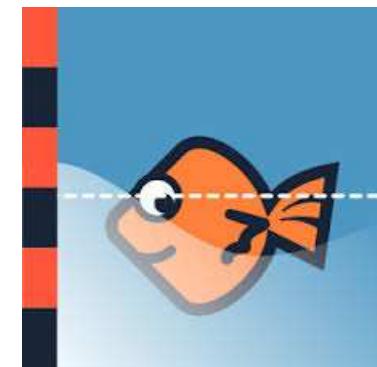
« Today: precision of [3] cm for the best geoid models to 10 cm for most of them. About 80 cm 25 years ago. »

Higher differences on strong reliefs and high oceanic variability areas

**Figure 3:** Differences between EGG2015 and EGM08 1'x1' grids, in meters.

- Denker, « A new European Gravimetric (Quasi)Geoid EGG2015 », 26th IUGG General Assembly (Session 3), Prague, June 22 – July 2, 2015.
- Ismail, « Determination de l'exactitude d'un géoïde gravimétrique », Astrophysique. PSL Research University, 2016. Français.

# Thank you



[https://www.ihc.int/mtg\\_docs/com\\_wg/IHOTC/IHOTC8/IHOTC8-3-6-1.pdf](https://www.ihc.int/mtg_docs/com_wg/IHOTC/IHOTC8/IHOTC8-3-6-1.pdf)

<https://www.geoportail.gouv.fr/donnees/litto3d>

<http://www.shom.fr/les-activites/projets/modele-numerique-terre-mer/>

<http://diffusion.shom.fr/produits/altimetrie-littorale>